

Errata

Simulation of Maneuvering Control During Underway Replenishment

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EQUATION (5) should be changed to read

$$Y_2^{(2)}(t) = \int_0^\infty \int_0^\infty \cos[(\omega_1 + \omega_2)t - (\epsilon(\omega_1) + \epsilon(\omega_2)) + \phi(\omega_1, \omega_2)] \sqrt{|H(\omega_1, \omega_2)|^2 S_x(\omega_1) S_x(\omega_2)} d\omega_1 d\omega_2 \\ + \int_0^\infty \int_0^\infty \cos[(\omega_1 - \omega_2)t - (\epsilon(\omega_1) - \epsilon(\omega_2)) + \phi(\omega_1, -\omega_2)] \sqrt{|H(\omega_1, -\omega_2)|^2 S_x(\omega_1) S_x(\omega_2)} d\omega_1 d\omega_2 \quad (5)$$

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